QUICK START GUIDE

EZ-ZONE® PM



For Part Numbers:

PM6 [C,R,B,J,N,E] _ [E,F,C] [J,C] - _ AAA _ _ _

Follow the steps in this quick start guide to wire and set up your new Watlow controller

> For assistance contact Watlow: www.watlow.com +1-(507)-494-5656 wintechsupport@watlow.com

0600-0056-0001 Rev. B

3

August 2014

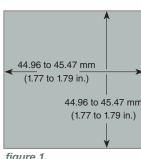
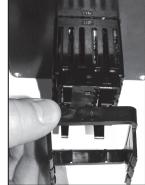


figure 1.

- 1. Make the panel cutout (see figure 1).
- 2. Remove the green screw terminal connectors from the
- 3. Insert the case assembly into the panel cutout and slide the mounting collar over the back of the controller (see figure 2).

INSTALLATION



- 4. Push the collar to the panel and secure into position.
- 5. Place the blade of a screwdriver against each of the four corners of the mounting collar and apply pressure to achieve IP65 seal (see figure 3).



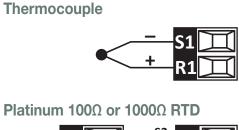
2

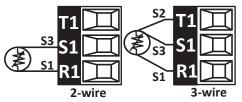
6. Reinstall the screw terminal connectors on the controller now or first connect field wiring as indicated in the steps that follow.

Caution: 🗥 Reinstall screw terminal connectors in their original

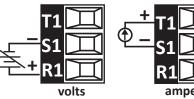
locations

SENSOR INPUT





Process Voltage or Current





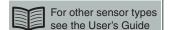
Connect your sensor

corresponding diagram.

as indicated in the

- RTD: 20Ω maximum round trip lead resistance
- Voltage: 0 to 50 mV or 0 to 10V@ 20kΩ
- Current: 0 to 20 mA @ 100Ω





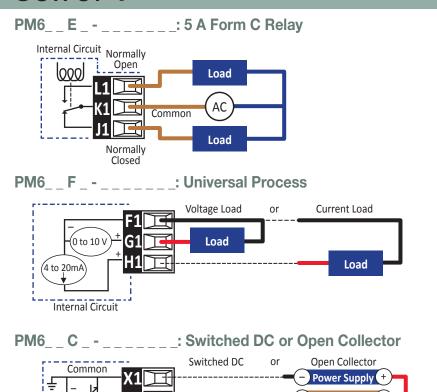
OUTPUT 1

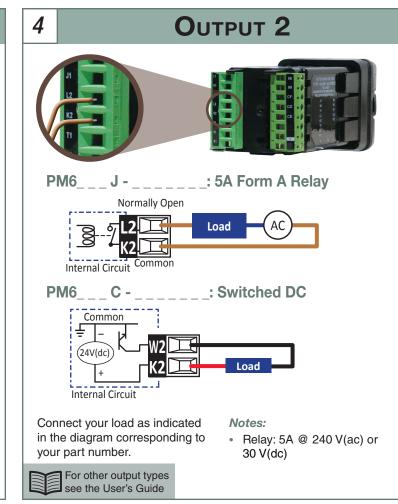


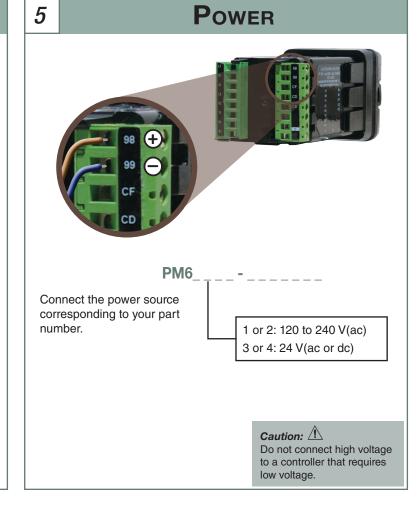
Connect your load as indicated in the diagram corresponding to your part number.

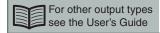
Notes:

- Relay: 5A @ 240 V(ac) or 30 V(dc)
- 0 to 20 mA: 800Ω max. load
- 0 to 10V: 1kΩ min. load









SET-UP GUIDE

USER INTERFACE

Infinity Key: - Exits to previous menu or page

Advance Kev: · Displays next menu item

· Hold both for Operation or Setup page

Change settings

Arrow Keys:

Special Display Characters

H = K, kh = H, ht = 1. i **⊔** = U, u u = V, vn = M. m∟յ = W, w $\frac{2}{2} = Z, z, 2$



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http://www.watlow.com/downloads/en/manuals/pmpmi.pdf

SET UP THE INPUT

Starting at the Home Page:



6

- . To enter the Setup Page press and hold 🔼 and until "5EL" appears in lower display.
- 2. Press (i) to enter the Analog Input menu.
- 3. Press (i) to view the Sensor Type setting.
 - 4. To change the sensor type from thermocouple "LC" to another type, press \(\simeq \) until the desired
 - 5. Press (i) and continue with the instructions for that sensor type below.



Thermocouple ($\not\vdash \not\sqsubseteq$):

type, press until the desired type is displayed.

To exit the Analog Input menu, press co twice to return to the Setup Page.



6. Set the number of RTD leads to 2 or 3 according to the sensor you are using. To change this press until the desired setting is displayed.

Note:

This takes about six seconds and you will see the operations page first. If you release the arrow keys too soon, press 🖾 once and then start again.

Sensor Types:

ĿΕ thermocouple $\rho \gamma_{\sigma}$ millivolts

uobE volts กาล milliamp

r 0.1H 100Ω RTD r 1.0H 1000Ω RTD

Pot potentiometer

analog input off

For other sensor types see the user manual.

Starting at the Setup Page:



oEPE

1. To view the output menu, press until "otpt" appears in upper display.

SET UP OUTPUTS FOR HEAT, COOL AND ALARM

- 2. To enter the Output menu press (1)
- 3. If the controller has more than one output, use \(\sigma \) and to select the output and press (i) to view the output's
- 4. To set what the output does in the controller, use \textsty and to select the desired function.
- 5. For hEAL or Look, press (1) and continue with the hardware specific options below (step 6). For an \mathbb{AL}^{n} , press \bigcirc and use \bigcirc and \bigcirc to select which alarm drives the output.

For other output functions or after selecting the alarm press to return to the top of the Output menu or press it twice to return to the Setup Page.



Form A, Form C or No-Arc Relay:

6. Use and to set the time base, the length of an onoff cycle.

Switched DC or Open Collector:



20.0

obb

6. Use \(\infty \) to set the method the controller uses to switch the output (Output Control).

For fixed time base use \(\sigma \) and \(\sigma \) to set the length of the

7. Press on to return to the top of the Output menu or press it twice to return to the Setup Page.

Output Functions:

heat control output cool control output

EnEA event output a event output b

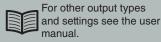
ALCO alarm output off

Output Control:

FĿЬ fixed time base: output switches per time base setting

uEb variable time base: output switches up to 20 times per second.





SET UP AN ALARM

Starting at the Setup Page:



To view the alarm menu press 🕡 until "AL [']" appears in the upper display.

Press (i) to enter the



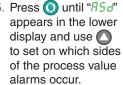
Press
to select the alarm and press (1) to view the alarm type.

alarm menu.



A5d

Press (to set the alarm type.



To return to the top of the Alarm menu, press or press it twice to return to the Setup page

Alarm Types:

PrRL process alarm: alarm set points are set directly.

dERL deviation alarm: alarm set points are set relative to the control loop's set point.

alarm does not occur.

Alarm Sides:

h₂9h high: alarm only when process is above high alarm set point.

Lold low: alarm only when process is below low alarm set point.

both both: high and low alarms are active.

SET ALARM SET POINTS

Starting at the Home Page:



1. To enter the Operations Page press and hold and until "oPEr" appears in lower display.



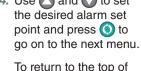
ALO

and/or

menu, press 🔼 until "ALP" appears in the upper display. Then press (i) to enter the alarm menu.



view the alarm set point. Use \(\sigma \) and \(\sigma \) to set the desired alarm set



the Alarm menu, press

or hold it for the

Home page.

To get to the home page, hold a until the process value and set point appear in the display.

Note:

Whether you can set a high alarm, a low alarm or both depends on how the Alarm Sides is set.

Note:

The low set point for a deviation type alarm should be set as a negative number.

Repeat for other alarms

LOOP CONTROL MODE/LOOP SET POINT

Set Loop Control Mode

Starting at the Home Page:



To view the control mode, press 🔘 until "[[]]" appears in the lower display.



2. Use 🔼 and 🕡 to change the control mode.

Adjust Loop Set Point

On the Home Page:



Use \text{\text{\text{\text{\text{and}}}} and \text{\text{\text{\text{to}}} to adjust the value in the lower display.

Hold the arrow key to change a number such as the set point at an accelerating rate. Release the key before reaching the desired setting and fine tune the value to avoid overshooting.

To get to the home page, hold a until the process value and set point appear in the display.

Note:

By default the control loop hEBL algorithim (hBB) is enabled for PID control. The [colling] algorithim ([R]) is set oFF by default. To enable, go to Setup Page and then to the Loop menu.

Control Modes:

outputs are off.

AULo automatic: loop adjusts output to make process match set point.

manual: control loop output power is set by the user in percent power. off: control loop



mode to auto and adjust the set point to the value at which you want the system tuned. 2. Press (i) until "AUL!"



Press to set the value to "YE5" and function.

EUni

start the auto-tuning Press on to return to

Caution: The autotune feature

turns on the loop's heat output until the process value exceeds 90% of the set point then turns the output off and repeats this. When finished the loop continues to control at the set point. Before starting the autotune. first consider if it is safe to do so at this time

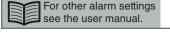
The system must be operational for

The upper display flashes "LUn !"

completed, the loop continues in

while the autotune function is

When the autotune function is auto mode.

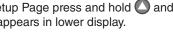


Repeat for other alarms









type is displayed.

6. To change the sensor type from "→" to another

100 Ω or 1000 Ω RTD (-0.1H or - 1.0H):



To exit the Analog Input menu, press on to return to the Setup Page.

11 AUTOTUNE THE CONTROL LOOP

Starting at the Home Page: L. Set the loop's control







the top of the Home Page.

Note:

autotuning to correctly select the PID settings.